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Numerical Simulation of the NASA High-Lift Trap Wing with the elsA CFD Software

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Outline



- elsA CFD software
- Summary of ONERA results on the Workshop Test Cases¹
- Evaluation of different grid generation approaches
- Off-body focus
- Conclusions



NASA Trap-Wing model



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The elsA solver



RANS computations

Cell-centered finite volume on structured multi-block meshes Time integration: Backward-Euler scheme with LU-SSOR relaxation Spatial discretization: Jameson's second-order centered scheme V-cycle multigrid technique Low-speed preconditioning

CGNS input and output format

Parallel mode (SGI Altix ICE 8200 EX)

Free-stream aerodynamic conditions:M=0.2Re=4.3M (based on MAC)







Summary of ONERA results on the workshop test cases

Grid convergence study



- Str-OnetoOne-A-v1 (supplied by HiLiftPW-1 Committee)
 - Coarse: 22x10⁶ nodes
 - Medium: 52x10⁶ nodes
 - Fine: 170x10⁶ nodes



Small variations between the different grid levels











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Flap deflection prediction study (2/3)





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Other investigated points of interest



- Computation strategy
 - Initialization from previous AoA necessary to avoid early lift break-down
- Turbulence modeling
 - SA, SA with rotation correction, k- ω SST (Menter, Kok, Wilcox) \rightarrow SA
- Flap/SOB separation
 - Little influence of grid refinement
- Far-field analysis (ffd72 software)

Cd

- Drag breakdown
 - $\alpha = 13 \text{ deg.}$
- Flap brackets effect



vare) Coarse Medium Fine



Evaluation of different grid generation approaches (Config 1, SA)



Overset approach



- Study limited to structured grids (although new capabilities from *elsA* version 3.4.03 include unstructured and hybrid grids consideration)
- Generation of 1-to-1 abutting structured grids considered too time consuming for 3D high lift configurations
- Need to evaluate and improve our overset methods
- "Classic" overset approach: insert slat and flap C-meshes in the glider grid



- Limitations:
 - important cell size discrepancies in the interpolation regions





Overset/Cartesian approach



- Near-body/off-body mesh partitioning approach
- Near-body O-grids
 - Generated with Pointwise (extrusion)
 - 18M points
 - Off-body Cartesian grids
 - Generated with the *elsA* suite
 - Octree-based
 - Patch grid BCs
 - Adaptation capabilities
 - 36M points







Force and moment comparisons (1/2)

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- Two main sources of differences between CFD and WT:
 - The slat and flap brackets are not included in the CFD
 - Fully turbulent calculations whereas the transition was not triggered in WT



Force and moment comparisons (2/2)



 Pitching moment prediction is the most challenging but probably the most subject to brackets/transition effects too



"Medium" grids and corresponding Mach number field (α =28°, η =50%) CFD High Lift Prediction Workshop



Str-OnetoOne-A-v1

52M points

Overset
32M points

Overset/Cartesian
 54M points

Skin pressure comparison (η=50%)



- Excellent agreement between all CFD results
- Good overall agreement with WT data



Skin pressure comparison (η=95%)



Tip pressure prediction more challenging than at mid-span



Skin pressure comparison (η=98%)



• The Overset/Cartesian approach performs great at α =13°, more mitigated results at α =28°



Stall mechanism







Off-body Focus



Grid adaptation





Baseline Overset/Cartesian grid 54M points

 Level 0 Cartesian grids adaptation based on eddy viscosity criterion
 69M points







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Brackets



- Initially, computations were planned on the brackets-on geometry with the Overset/Cartesian approach
- A 88M points grid was built, but convergence issues were encountered for AoA above 6°



Conclusions



Workshop test cases

- Grid refinement study: low sensitivity of the selected mesh to grid refinement with the *elsA* software.
- Flap deflection study: good overall agreement with WT data, although the force and moment increments due to flap deflection are difficult to predict.

Grid comparison study

- Motivated by the need to evaluate and improve our overset methods.
- Good overall agreement between the results obtained on the three grids.
- CLmax over-predicted by 1 to 2% depending on the grid type.
- Differences mainly observed in tip region and in stall behavior.
- Hard to conclude on the superiority of an approach over the other in terms of absolute prediction accuracy due to differences between WT and CFD conditions.
- Overset/Cartesian approach offers a good compromise between meshing effort and solution quality.



What can be expected from HiLiftPW-2



- Selected test cases based on the DLR F11 configuration (EUROLIFT project)
- More realistic transport aircraft high-lift configuration
- Reynolds number scale effect
 assessment
- Good opportunity to confirm the maturity of our overset tools and possibly to test our hybrid mesh generation capabilities
- Which level of geometrical complexity (brackets, nacelle, strakes)?



DLR F11 WT model





Thank you for your attention !

Any questions?



