

Engineering, Operations & Technology Boeing Research & Technology

Comparison of Fixed and Adaptive Mesh Results for HiLiftPW-3

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Summary of cases completed: GGNS, SA-QCR

Case (HL-CRM)	Alpha=8, Fully turb, grid study	Alpha=16, Fully turb, grid study	Other
1a (full gap)	yes	yes	
1b (full gap w adaption)	yes	yes	
1c (partial seal)	yes	yes	
1d (partial seal w adaption)	yes	yes	

Case (JSM)	Polar, Fully turb	Polar, specified transition	Polar, w transition prediction	Other
2a (no nacelle)	yes	no	no	
2b (no nacelle w adaption)	yes	no	no	
2c (with nacelle)	yes	no	no	
2d (with nacelle w adaption)	yes	no	no	

Case (DSMA661)	2D Verification study	Other
3	yes	
Other	adapted	

Summary of code and numerics used

GGNS¹ (General Geometry Navier-Stokes)

- Tet-only unstructured grids
- Stabilized finite-element SUPG, second order
- Exact Jacobians, Newton-Raphson algorithm
- Linesearch. Time marching to steady state
- PETSc framework for linear and non-linear solvers
- Machine-zero converged steady state solutions
- Fully turbulent solutions : SA-QCR turbulence model

EPIC² (Edge Primitive Insertion and Collapse)

- Anisotropic metric-based tetrahedral grid adaptation
- Utilizes edge based operators to coarsen/refine surface and volume mesh to match a target metric field
- Metric field derived from solver error estimate
- 1) Kamenetskiy, D. *et al.*, "Numerical Evidence of Multiple Solutions for the Reynolds-Averaged Navier–Stokes Equations," AIAA Journal Vol. 52, No. 8 (2014), pp. 1686-1698
- 2) Michal, T. and Krakos, J., "Anisotropic Mesh Adaptation through Edge Primitive Operations," AIAA Paper 2012-159, 2012

Brief overview of grid system(s)

Grid System	Case(s)	If committee grid, report any problems/issues If user grid, reason for generating grid system
Committee (B1-HLCRM_UnstrTet_PW)	1a, 1c	No solver problems/issues
User (a-HLCRM_AdaptedTet_EPIC)	1b, 1d	Generated adapted grid system for each geometry/AOA
Committee (C1-JSM_UnstrTet_VGRID)	2a, 2c	No solver problems/issues
User (JSM_AdaptedTet_EPIC)	2b, 2d	Generated adapted grid system for each geometry/AOA

Committee Grids (B1-HLCRM and C1-JSM)

- B1-HLCRM fixed grid family of grids (Pointwise)
- C1-JSM single fixed grids for Nacelle on/off geometries (VGRID)

Adapted Grids

- Adapted to Mach Hessian, directly on IGES geometry
- Fully automated family of grids from initial grid and geometry

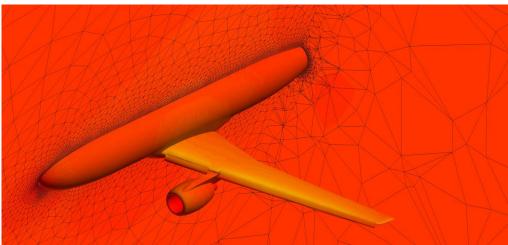
HLCRM Geometry Issues



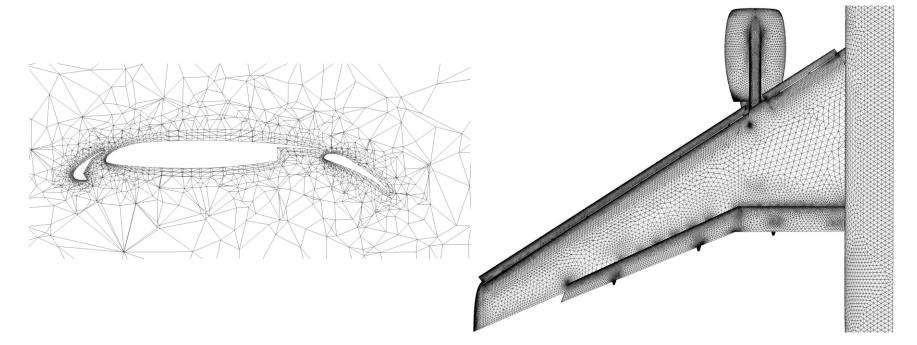
- Highly resolved definition of Wing/Body fairing high computed curvature
- Trimming curve offset (0.02") between
 - inboard flap lower surface and sides
 - slat trailing edge and slat upper/lower surfaces
- Offset issues were introduced during geometry prep, corrected and rerun Copyright © 2016 Boeing. All rights reserved.

Example Adaptation Sequence JSM case2d, Mach 0.172, Re=1.93M, α=14.54° Grid Level 0

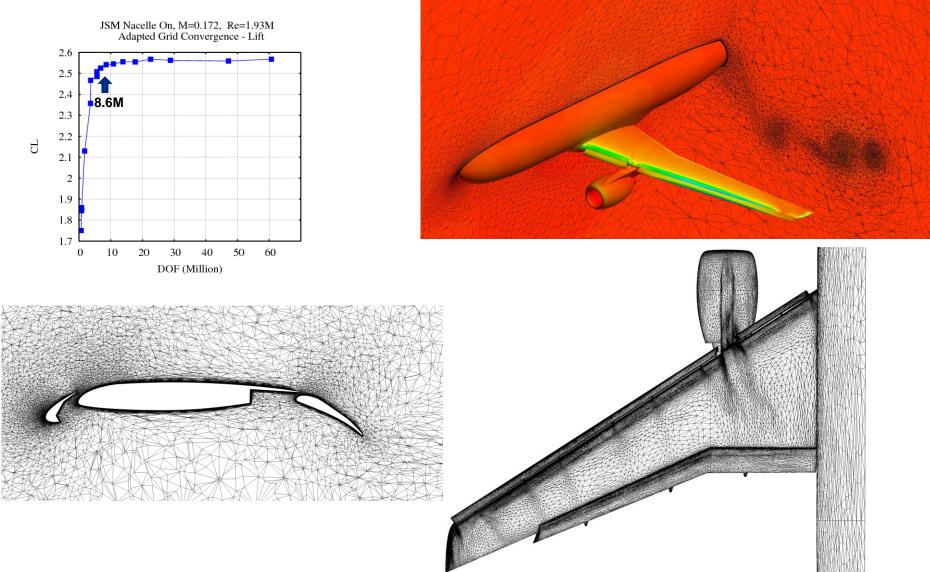
- Start with coarse initial grid
- Generate solution and error estimate
- Derive anisotropic sizing field that distributes mesh DOF to equilibrate error over domain



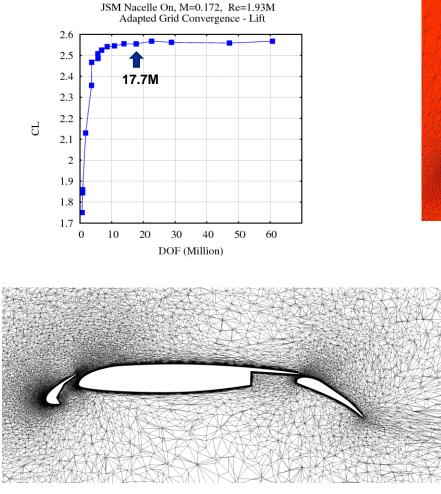
Initial Mesh Nodes=678K

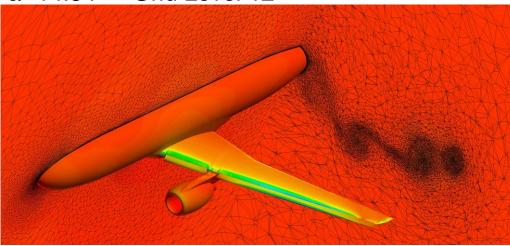


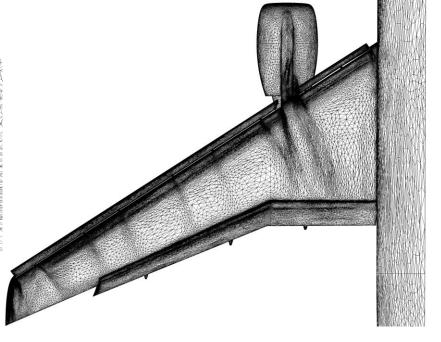
Example Adaptation Sequence JSM case2d, Mach 0.172, Re=1.93M, <u>α=14.54°</u> Grid Level 9



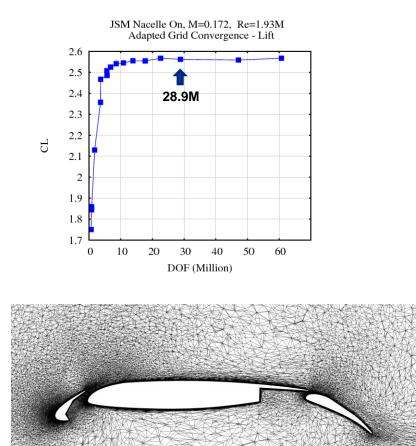
Example Adaptation Sequence JSM case2d, Mach 0.172, Re=1.93M, <u>α=14.54°</u> Grid Level 12

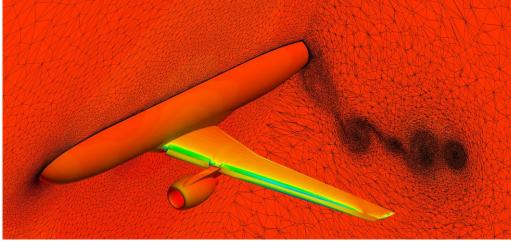


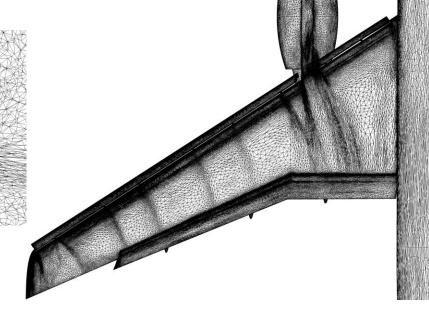




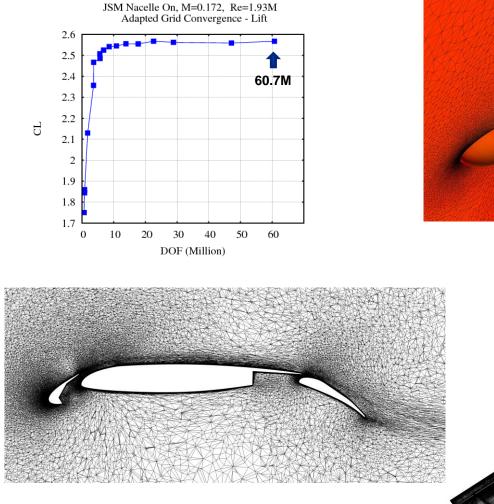
Example Adaptation Sequence JSM case2d, Mach 0.172, Re=1.93M, α=14.54° Grid Level 14

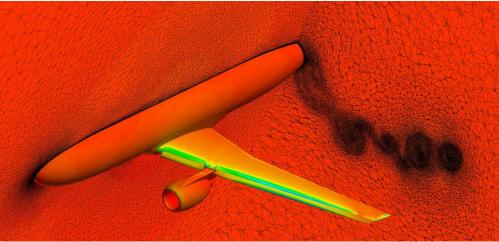


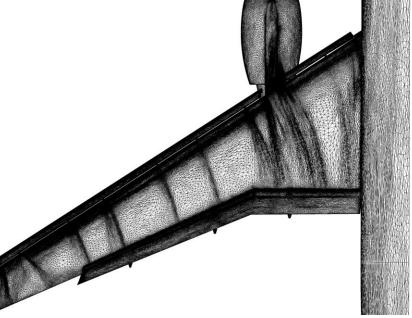




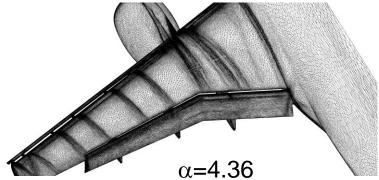
Example Adaptation Sequence JSM case2d, Mach 0.172, Re=1.93M, α=14.54° Grid Level 17

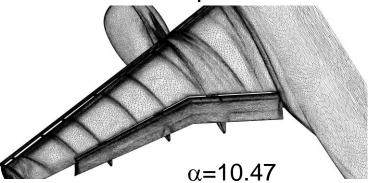


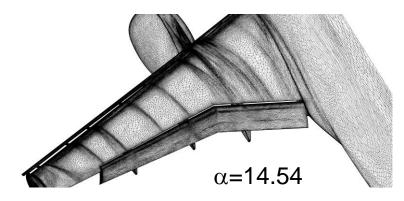


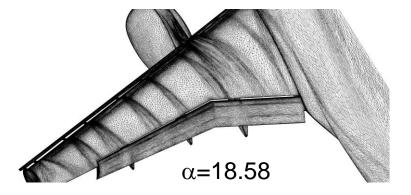


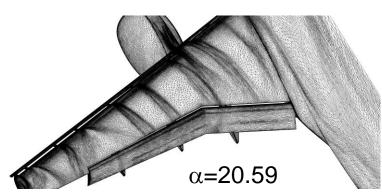
Adaptive Grid Generated at Each Solution Point JSM Adapted Surface Grids for Angle of Attack Sweep

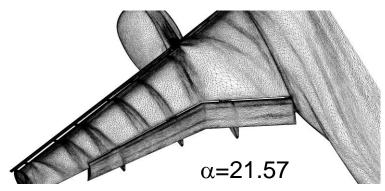






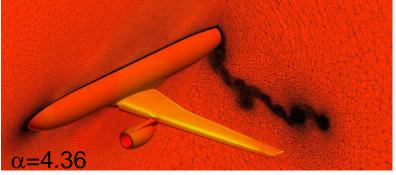


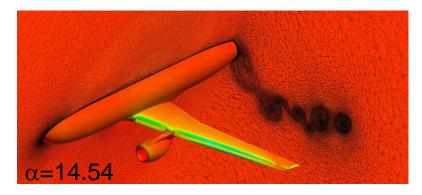


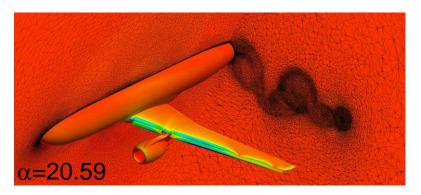


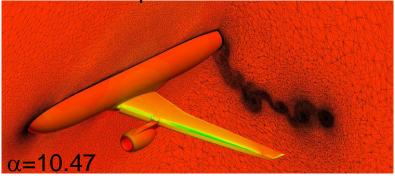
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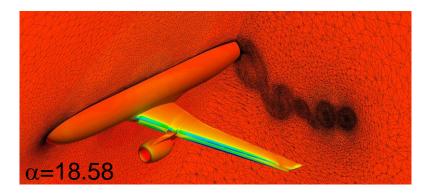
Adaptive Grid Generated at Each Solution Point JSM Adapted Wake Grids for Angle of Attack Sweep

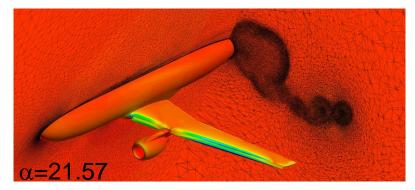








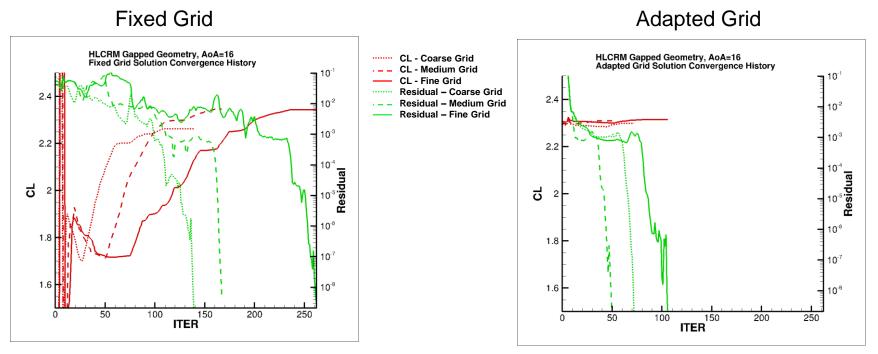




HL-CRM Cases (Gapped and Partially Sealed)

- Objective: Compare adapted and fixed grid solutions
- Fixed grid family: B1-HLCRM_UnstrTet_PW
- Adapted grid family: a-HLCRM_AdaptedTet_EPIC

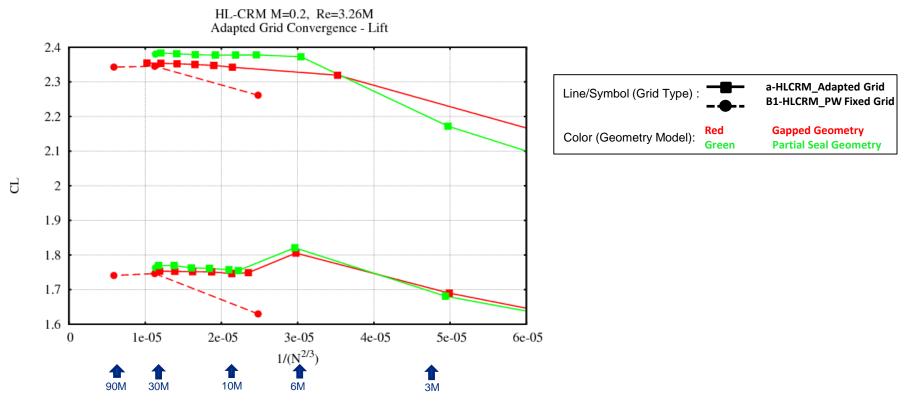
Sample Solution Convergence



Machine zero residual convergence achieved for nearly all solutions

Adapted grid solutions converge in fewer iterations (better initial guess)

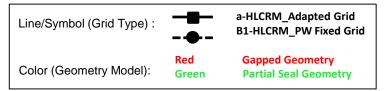
HL-CRM - Fixed and Adapted Grid Convergence



Adapted solutions converge to near constant lift (~ 10M DOF)

- Slight increase in CL with grid resolution continues
- Consistent seal-gap increment with increasing grid resolution
- Insufficient data to evaluate fixed grid convergence
 - Non-asymptotic convergence for the gapped geometry
 - One data point for increment

HL-CRM Computed Increment Sealed-Gapped



30M

Lift Convergence, $\alpha = 16^{\circ}$ Lift Convergence, $\alpha = 8^{\circ}$ 1.84 2.5 1.82 adapt grid 2.45 $\Delta CL = 0.016$ 1.8adapt grid 1.78 $\Delta CL = 0.029$ 2.4 1.76 1.74 D 2.35 1.72 1.7 2.3 fixed grid fixed grid 1.68△ CL = 0.017 $\Delta CL = 0.035$ 1.66 2.25 1.64 2.2 1.62 2.5e-05 5e-06 1.5e-05 2e-05 2.5e-05 3e-05 5e-06 1.5e-05 2e-05 0 1e-05 0 1e-05 3e-05 $1/(N^{2/3})$ $1/(N^{2/3})$

Adaptive results provide richer data set for measuring increment (less uncertainty)

30M

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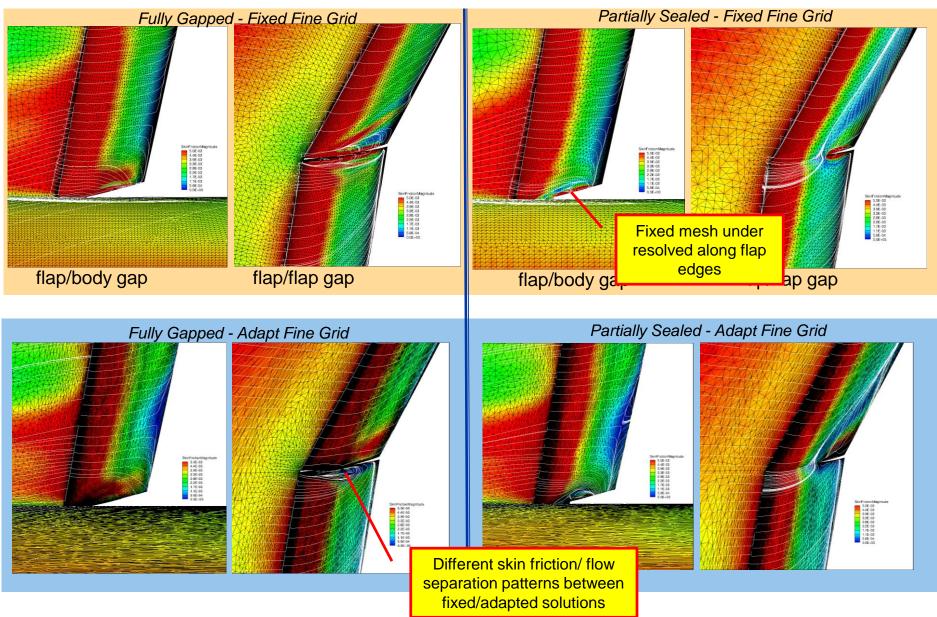
6M

10M

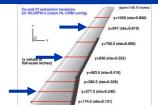
6M

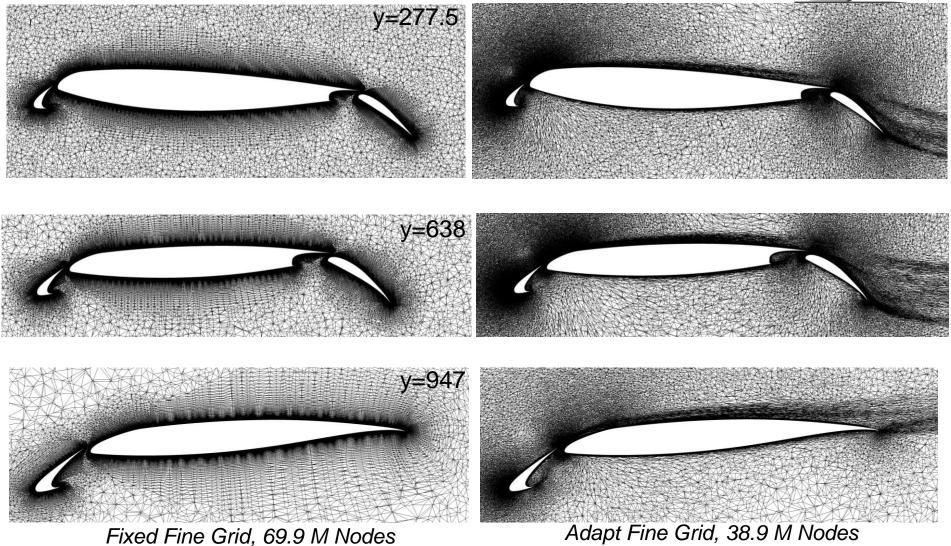
10M

Solution Comparison in Flap Gaps, HLCRM AoA=16 degrees



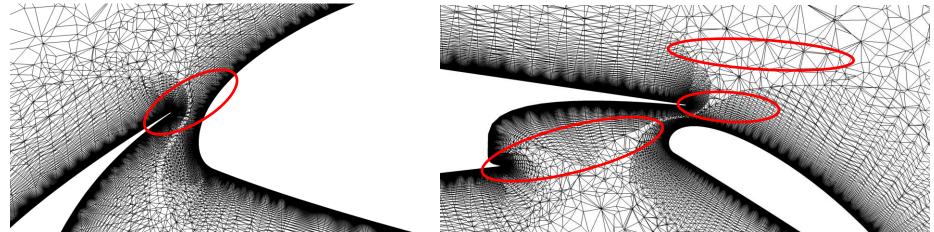
Comparison of Fixed and Adapted Volume Grids HLCRM Gapped AoA=16 degrees



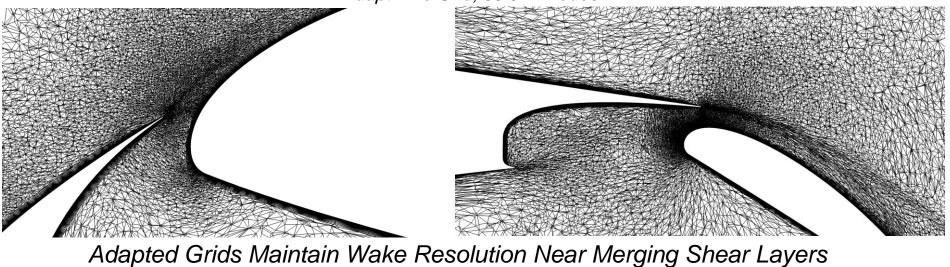


Fixed and Adapted Grid Slat and Wing Wakes y=638 HLCRM Gapped AoA=16 degrees

Fixed Fine Grid, 69.9 M Nodes



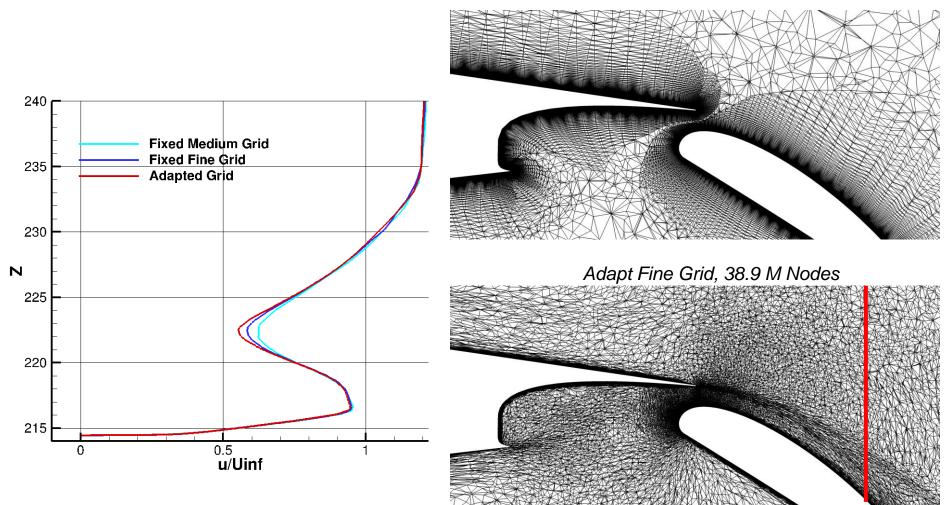
Adapt Fine Grid, 38.9 M Nodes



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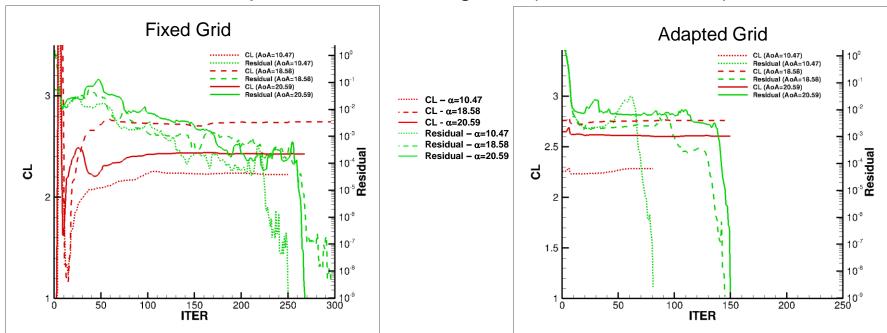
Fixed and Adapted Grid Velocity Profile x=1615, y=638 HLCRM Gapped AoA=16 degrees

Fixed Fine Grid, 69.9 M Nodes



JAXA JSM Cases with and without Nacelle

- Objective: Compare adapted and fixed grid solutions
- Fixed grid family: C1-JSM_UnstrTet_VGRID
- Adapted grid family: JSM_AdaptedTet_EPIC

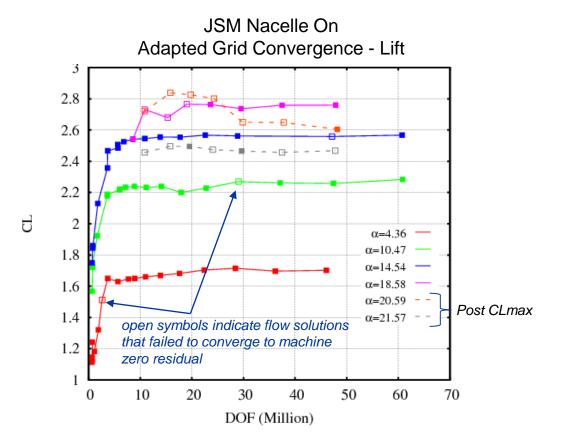


Sample Solution Convergence (JSM with Nacelle)

- Almost all solutions converge to machine zero residuals at pre-stall angle of attack
- Post stall solutions do not converge as well
- Adapted grid solutions converge in fewer iterations compared to fixed grid

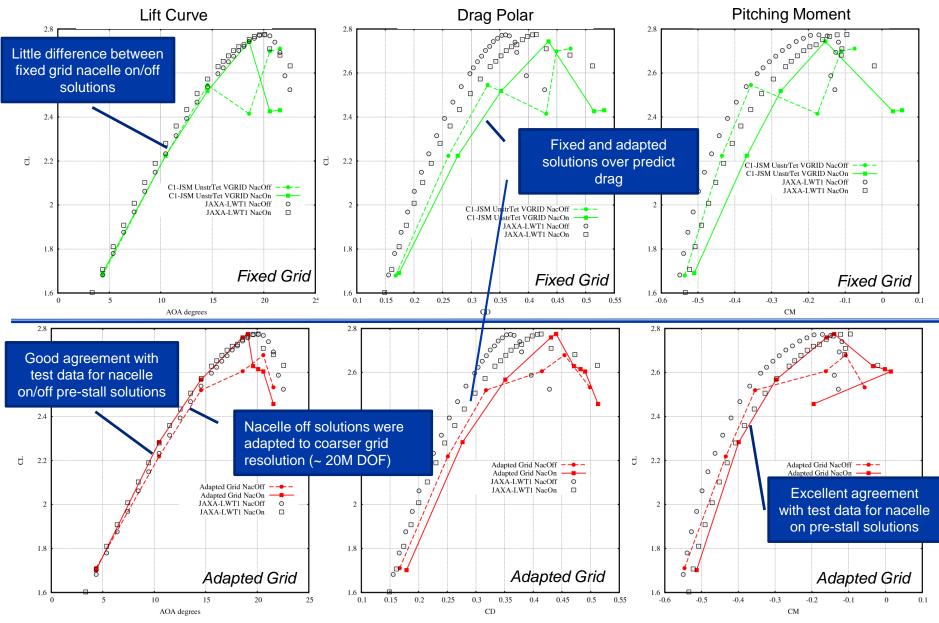
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JAXA JSM – Adapted Grid Convergence



- Rapid convergence to ~ 10M DOF followed by slow convergence to final lift
- Pre stall solutions convergence to near constant lift
- Post stall solutions not as close to grid converged
- Multiple solution branches complicate adaptive process

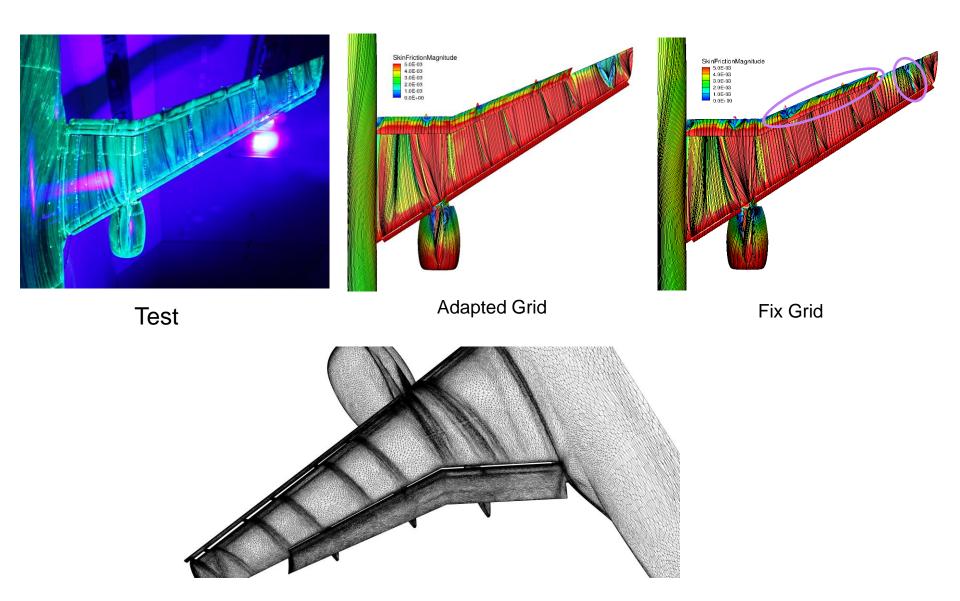
JSM Nacelle On/Off - Forces and Pitching Moment



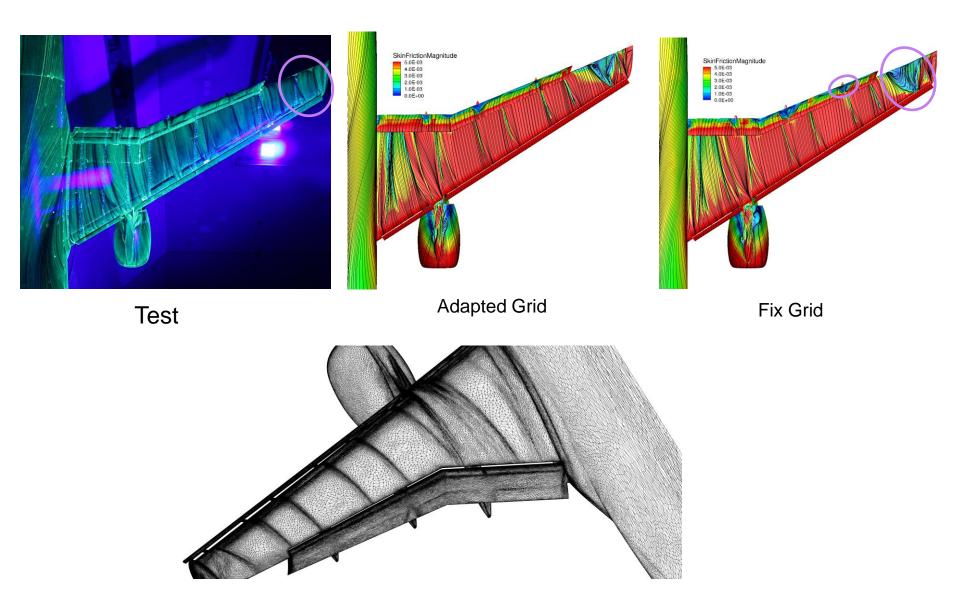
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HiLiftPW-3, Denver CO, June 2017

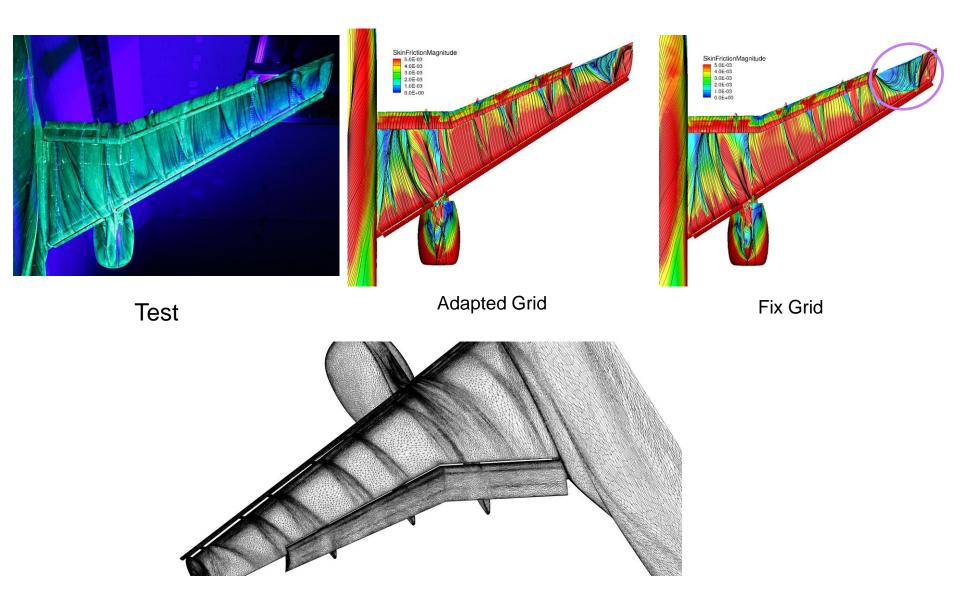
JSM Oil Flows AoA=4.36°



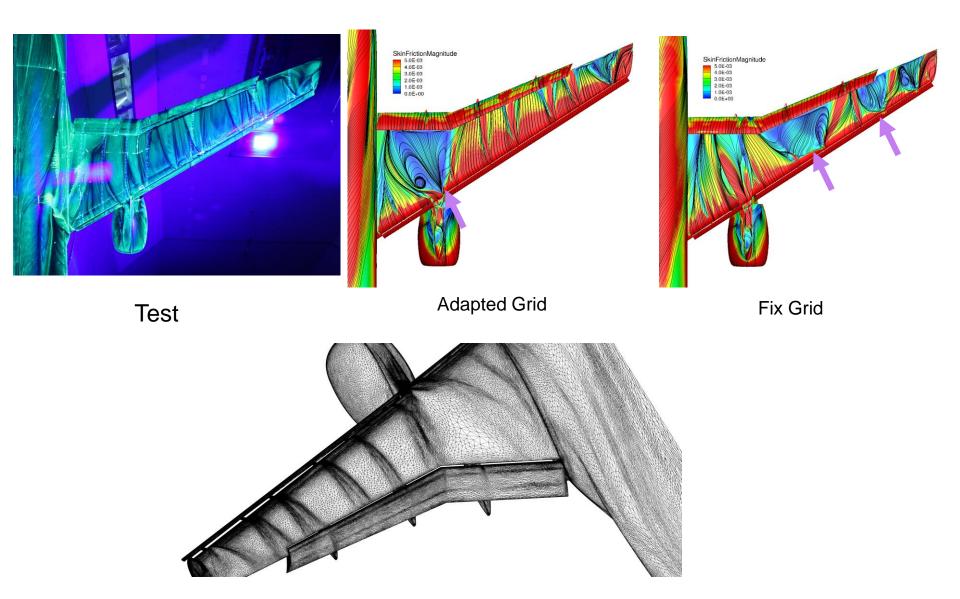
JSM Oil Flows AoA=10.47°



JSM Oil Flows AoA=18.59°

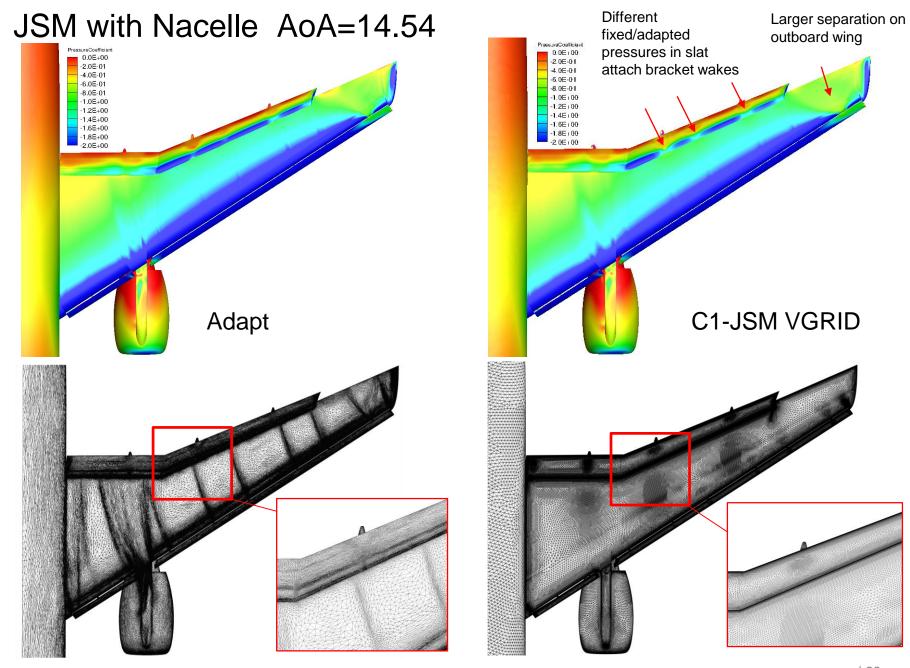


JSM Oil Flows AoA=21.57°



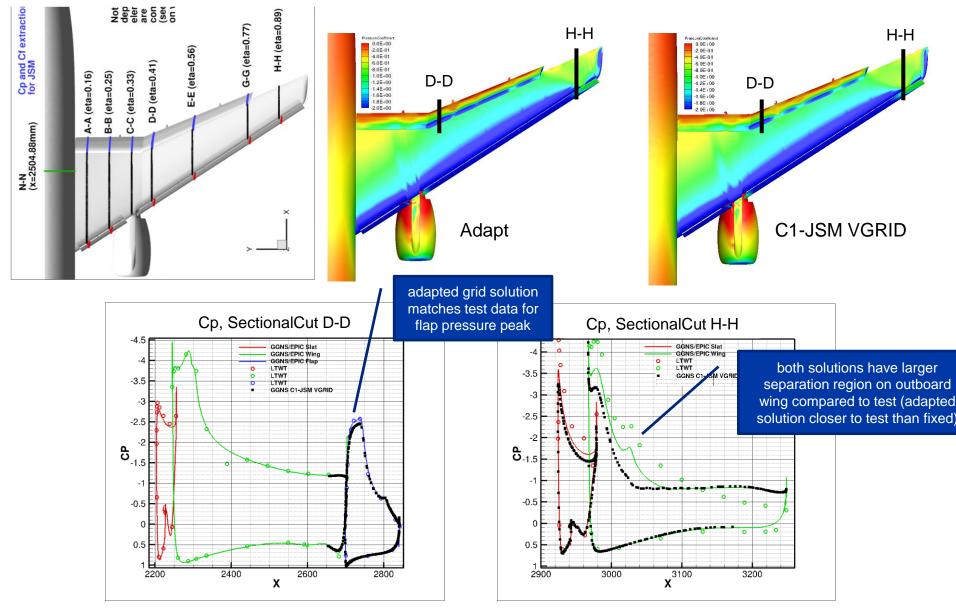


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JSM with Nacelle AoA=14.54



Summary

Adaptive Mesh Solutions

- ✓ Machine zero solution residual convergence obtained for most pre-stall solutions
- Results approach constant lift with grid size for all cases

HLCRM Fixed/Adapted Grid Comparison

- ✓ Adapted grids better at resolving merging shear layers and details of flap gaps
- Better grid convergence achieved for adapted grid results even at coarse grid sizes
- ✓ Adaptive approach provided richer data set for measuring gap/seal increment

JSM Fixed/Adapted Grid Comparison

- Adapted results better at predicting slat attach wake impact on flap surface pressure and outboard wing separation
- ✓ Adapted results predict nacelle on/off CL increment accurately compared to fixed grid
- Adaptation did not improve CLmax prediction, both approaches predicted angle of attack at CLmax ~ 1° early with nacelle and > 2° early without nacelle

Adaptive Meshing Provided Several Advantages

- Automatic generation of consistent mesh family saved weeks of labor by an expert user compared to fixed grid approach
- ✓ No a priori solution knowledge required
- Reduced solution uncertainty due to mesh

